

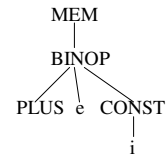
# COMPILERS

## Instruction Selection

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### Introduction

- IR expresses only one operation in each node.
- MC performs several instructions in an instruction.
  - e.g., fetch and add



### Preliminaries

- Express each machine instruction as a fragment of an IR tree – “tree pattern”.
- Instruction selection is then equivalent to tiling the tree with a minimal set of tree patterns.

### Jouette Architecture

Name	Effect	Trees
—	—	TEMP
ADD	$r_i \leftarrow r_j + r_k$	
MUL	$r_i \leftarrow r_j * r_k$	
SUB	$r_i \leftarrow r_j - r_k$	
DIV	$r_i \leftarrow r_j / r_k$	
ADDI	$r_i \leftarrow r_j + c$	
SUBI	$r_i \leftarrow r_j - c$	
LOAD	$r_i \leftarrow M[r_j + c]$	

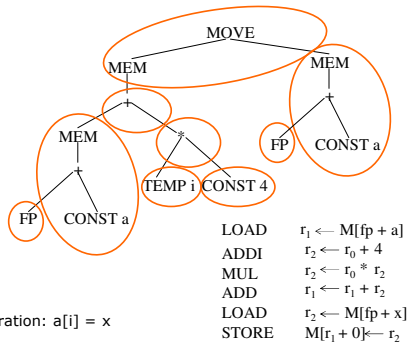
### Jouette Architecture

Name	Effect	Trees
STORE	$M[r_j + c] \leftarrow r_i$	
MOVEM	$M[r_j] \leftarrow M[r_i]$	

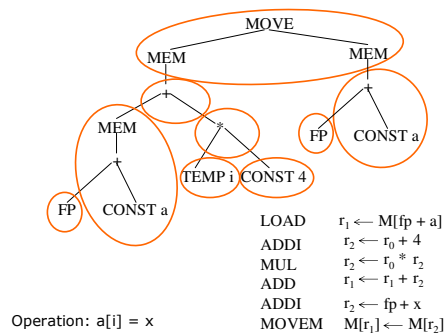
### Instruction Selection

- The concept of instruction selection is tiling.
- Tiles are the set of tree patterns corresponding to legal machine instructions.
- We want to cover the tree with non-overlapping tiles.
- Note: We wont worry about which registers to use - yet.

## Tiled Tree 1



## Tiled Tree 2



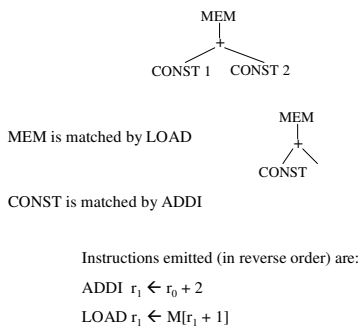
## Optimum and Optimal Tilings

- Best tiling corresponds to least cost instruction sequence.
- Each instructions is costed (somehow).
- Optimum tiling
  - tiles sum to lowest possible value
- Optimal tiling
  - no two adjacent tiles can be combined to a tile of lower cost
- Note: Optimum tiling is Optimal, but not vice versa!

## Maximal Munch Algorithm

- Start at the root.
- Find the largest tile that fits.
- Cover the root and possibly several other nodes with this tile.
- Repeat for each subtree.
- Generates instructions in reverse order.
- If two tiles of equal size match the current node, choose either.

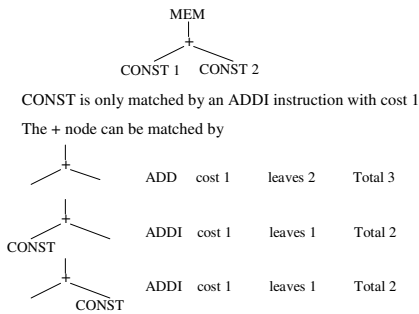
## Maximal Munch Example



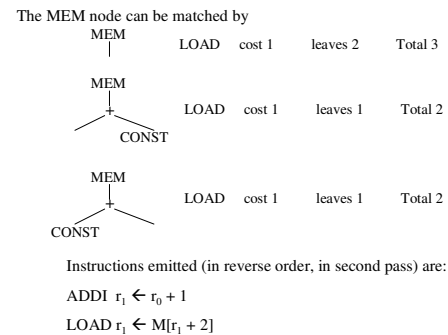
## Dynamic Programming Algorithm

- Assign a cost to every node.
  - Sum of instruction costs of the best instruction sequence that can tile that subtree.
- For each node  $n$ , proceeding bottom-up:
  - For each tile  $t$  of cost  $c$  that matches at  $n$  there will be zero or more subtrees,  $s_i$ , that correspond to the leaves (bottom edges) of the tile.
    - Cost of matching  $t$  is cost of  $t$  + sum of costs of all child trees of  $t$
  - Assign tile with minimum cost to  $n$ .
- Walk tree from root and emit instructions for assigned tiles.

## Dynamic Programming Example 1/2



## Dynamic Programming Example 2/2



## Efficiency of Algorithms

- Assume (on average):
  - T tiles
  - K non-leaf nodes in matching tile
  - Kp is largest number of nodes to check to find matching tile
  - Tp no of different tiles matching at each node
  - N nodes in tree
- Cost of MM:  $O((Kp + Tp)N/K)$
- Cost of DP:  $O((Kp + Tp)N)$
- In both cases, with Kp, Tp, K constant
  - $O(N)$

## Handling CISC Machine Code

- Fewer registers:
  - E.g., Pentium has only 6 general registers
  - Allocate TEMPs and solve problem later!
- Register use is restricted:
  - E.g., MUL on Pentium requires use of eax
  - Introduce additional LOAD/MOVE instructions to copy values.
- Complex addressing modes:
  - E.g., Pentium allows ADD [ebp-8],ecx
  - Simple code generation still works, but is not as size-efficient, and can trash registers.

## Implementation Issues

- If registers are allocated after instruction selection, generated code must have "holes".
  - Assembly code template: LOAD d0,s0
  - List of source registers
  - List of destination registers
    - Including registers trashed by instruction (e.g., return address and return value registers for CALLs)
- Register allocation will then fill in the holes, by (simplistically) matching source and destination registers and eliminating redundancy.